

L Number	Hits	Search Text	DB	Time stamp
1	420	mark or dot)near2((grid or lattice or coordinate)adj2 point	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:52
2	191	(mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:31
3	1505846	((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:44
4	110	(mark or dot)near2((grid or lattice or coordinate)adj2 point) and ((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:25
5	0	((mark or dot)near2((grid or lattice or coordinate)adj2 point) and ((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4)) and identify\$3 and raster near3 pattern	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:53
13	0	((mark or dot)near2((grid or lattice or coordinate)adj2 point) and ((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4)) and identify\$3 and raster near3(pattern or lines)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:38
14	110	((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4 and ((mark or dot)near2((grid or lattice or coordinate)adj2 point) and ((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (((mark or dot)near2((grid or lattice or coordinate)adj2 point) and (determin\$4 or detect\$4)adj2(locat\$3 or posit\$3 or address or coordinate)) and (fourier or cosine or sine)adj\$3 transform\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:44
15	2	(mark or dot)near2((grid or lattice or coordinate)adj2 point) and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:49

16	34	(sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:54
17	1	((sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern) and (mark or dot)near2((grid or lattice or coordinate)adj2 point)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:53
18	13	((sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern) and((grid or lattice or coordinate)adj2 point)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:53
19	11	((sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern) and((grid or lattice or coordinate)adj2 point)) and identify\$3 and raster near3 pattern	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:54
20	9	((sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern) and((grid or lattice or coordinate)adj2 point)) and identify\$3 and raster near3 pattern) and partial near3 surface and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern and posit\$3 near3 code	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:58
21	0	((sens\$4 or detector\$4 or ccd or sensor\$1 or camera)and posit\$3 and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern) and((grid or lattice or coordinate)adj2 point)) and identify\$3 and raster near3 pattern) and partial near3 surface and (mark or dot)near2(plurality or plural\$3)and intersect\$3 and raster near2 pattern and posit\$3 near3 code) and @ad<20000405	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/11 14:57